# The Capacity of Quiver Representations and Brascamp-Lieb Constants 

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Let $Q$ be a bipartite quiver, $V$ a real representation of $Q$, and $\sigma$ an integral weight of $Q$ orthogonal to the dimension vector of $V$. Guided by quiver invariant theoretic considerations, we introduce the Brascamp-Lieb (BL) operator $T_{V, \sigma}$ associated to ( $V, \sigma$ ) and study its capacity, denoted by $\mathbf{D}_{Q}(V, \sigma)$. When $Q$ is the $m$-subspace quiver, the capacity of quiver data is intimately related to the BL constants that occur in the $m$-multilinear BL inequality in analysis. We show that the positivity of $\mathbf{D}_{Q}(V, \sigma)$ is equivalent to the $\sigma$-semi-stability of $V$. We also find a character formula for $\mathbf{D}_{Q}(V, \sigma)$ whenever it is positive. Our main tool is a quiver version of a celebrated result of KempfNess on closed orbits in invariant theory. This result leads us to consider certain real algebraic varieties that carry information relevant to our main objects of study. It allows us to express the capacity of quiver data in terms of the character induced by $\sigma$ and sample points of the varieties involved. Furthermore, we use this character formula to prove a factorization of the capacity of quiver data. We also show that the existence of gaussian extremals for $(V, \sigma)$ is equivalent to $V$ being $\sigma$-polystable and that the uniqueness of gaussian extremals implies that $V$ is $\sigma$-stable. Finally, we explain how to find the gaussian extremals of a gaussian-extremisable datum ( $V, \sigma$ ) using the algebraic variety associated to $(V, \sigma)$.

## 1 Introduction

### 1.1 Motivation

The motivation in this paper goes back to the celebrated Brascamp-Lieb (BL) inequality in harmonic analysis. Let $m, d, d_{1}, \ldots, d_{m} \geq 1$ be integers and $\mathbf{p}=\left(p_{1}, \ldots, p_{m}\right)$ an $m$ tuple of non-negative real numbers such that $d=\sum_{j=1}^{m} p_{j} d_{j}$. Let $\mathbf{V}=\left(V_{j}\right)_{j=1}^{m} \in \prod_{j=1}^{m} \mathbb{R}^{d_{j} \times d}$ be an $m$-tuple of matrices. The BL constant associated to the datum ( $\mathbf{V}, \mathbf{p}$ ) is the best constant for which the BL inequality

$$
\begin{equation*}
\int_{\mathbb{R}^{d}} \prod_{j=1}^{m}\left(f_{j} \circ V_{j}\right)^{p_{j}} \leq \mathrm{BL}(\mathbf{V}, \mathbf{p}) \prod_{j=1}^{m}\left(\int_{\mathbb{R}^{d_{j}}} f_{j}\right)^{p_{j}} \tag{1}
\end{equation*}
$$

holds for all non-negative integrable functions $f_{j}: \mathbb{R}^{d_{j}} \rightarrow \mathbb{R}, j \in[m]$. The constant $\mathrm{BL}(\mathbf{V}, \mathbf{p})$ can be infinite, in which case the BL inequality is rather vacuous. However, in the finite case, the BL inequality generalizes many classical inequalities in harmonic analysis such as the Hölder, Young's convolution, and Loomis-Whitney inequalities, just to name a few. Furthermore, the BL constants/inequalities permeate various other areas of mathematics, including convex geometry, functional analysis, and computer science. See for example [1-6, 11, 14, 15, 19].

A systematic study of BL constants has been undertaken by J. Bennett, A. Carbery, M. Christ, and T. Tao in [4] where the authors prove many important results. For example, they give necessary and sufficient conditions for the finiteness of $\mathrm{BL}(\mathbf{V}, \mathbf{p})$. The linear maps $V_{j}, j \in[m]$, that appear in (1) can be encoded as a representation of the bipartite directed graph $\mathcal{Q}_{m}$, also known as the $m$-subspace quiver, as follows:


Then [4, Theorem 1.13] simply says that $\operatorname{BL}(\mathbf{V}, \mathbf{p})<\infty$ if and only if V is a semistable representation of $\mathcal{Q}_{m}$ with respect to the weight defined by $\mathbf{p}$. Furthermore, the following comment appears in [4, Section 4]: "It is likely that the deeper theory of such [quiver] representations is of relevance to this [Brascamp-Lieb] theory, but we do not pursue these connections here."

In this paper, we study BL constants within the general framework of quiver invariant theory.

### 1.2 Our results

We briefly recall just enough terminology to state our main results, with more detailed background found in Section 2. Let $Q$ be a connected quiver with set of vertices $O_{0}$ and set of arrows $Q_{1}$. For an arrow $a \in Q_{1}$, we denote by $t a$ and $h a$, its tail and head, respectively. We represent $Q$ as a directed graph with set of vertices $Q_{0}$ and directed edges $a: t a \rightarrow$ ha for every $a \in O_{1}$. A real representation $V$ of $Q$ assigns a finite-dimensional real vector space $V(x)$ to every vertex $x \in O_{0}$ and a linear map $V(a): V(t a) \rightarrow V(h a)$ to every arrow $a \in Q_{1}$. After fixing bases for the vector spaces $V(x), x \in Q_{0}$, we often think of the linear maps $V(a), a \in Q_{1}$, as matrices of appropriate size. The dimension vector of a representation $V$ of $Q$ is $\operatorname{dim} V:=\left(\operatorname{dim}_{\mathbb{R}} V(x)\right)_{x \in Q_{0}} \in \mathbb{N}^{Q_{0}}$.

Let $\sigma \in \mathbb{Z}^{Q_{0}}$ be an integral weight of $Q$. A representation $V$ of $Q$ is said to be $\sigma$-semi-stable if $\sigma \cdot \operatorname{dim} V=0$ and $\sigma \cdot \operatorname{dim} V^{\prime} \leq 0$ for all subrepresentations $V^{\prime} \leq V$. We say that $V$ is $\sigma$-stable if $\sigma \cdot \operatorname{dim} V=0$ and $\sigma \cdot \operatorname{dim} V^{\prime}<0$ for all proper subrepresentations $V^{\prime}$ of $V$. We call a representation $\sigma$-polystable if it is a finite direct sum of $\sigma$-stable representations.

For our purposes, we can simply assume that $Q$ is bipartite (see Remark 6). This means that $Q_{0}$ is the disjoint union of two subsets $Q_{0}^{+}=\left\{v_{1}, \ldots, v_{n}\right\}$ and $Q_{0}^{-}=$ $\left\{w_{1}, \ldots, w_{m}\right\}$, and all arrows in $Q$ go from $Q_{0}^{+}$to $Q_{0}^{-}$. Furthermore, we assume that $\sigma$ is positive on $Q_{0}^{+}$and negative on $Q_{0}^{-}$.

Let $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ be a dimension vector such that $\sigma \cdot \mathbf{d}=0$, and let $V$ be a d-dimensional representation of $Q$ with $V(x)=\mathbb{R}^{\mathbf{d}(x)}, \forall x \in Q_{0}$, and $V(a) \in \mathbb{R}^{\mathbf{d}(h a) \times \mathbf{d}(t a)}, \forall a \in Q_{1}$. Guided by invariant theoretic considerations and [19, Construction 4.2], we associate to the quiver datum $(V, \sigma)$, the so-called BL operator $T_{V, \sigma}$ (see Definition 4). This is a completely positive operator whose Kraus operators are certain blow-ups of the matrices $V(a), a \in Q_{1}$.

We define the capacity of $(V, \sigma)$, denoted by $\mathbf{D}_{Q}(V, \sigma)$, to be the capacity of the operator $T_{V, \sigma}$. The determinantal formula for $\mathbf{D}_{Q}(V, \mathbf{p})$ in Lemma 8 leads us to the definition of the $B L$ constant $\mathrm{BL}_{Q}(V, \mathbf{p})$ associated to ( $V, \mathbf{p}$ ) (see Definition 10). In fact, when $Q=\mathcal{Q}_{m}$ is the $m$-subspace quiver, we recover the classical BL constants.

Our first result gives necessary and sufficient conditions for the positivity of the capacity of a quiver datum.

Theorem 1. Let $Q$ be a bipartite quiver and $(V, \sigma)$ a quiver datum. Then

$$
\mathbf{D}_{Q}(V, \sigma)>0 \Longleftrightarrow V \text { is } \sigma \text {-semi-stable. }
$$

In [19, Corollary 3.17], the authors have found a deterministic polynomial time algorithm for deciding the positivity of the capacity of a completely positive operator. This algorithm combined with Theorem 1 yields a $\operatorname{poly}(b, N)$ time (deterministic) algorithm to check if $V$ is $\sigma$-semi-stable where $b$ is the total bit size of $V$ and $N=$ $\sum_{i=1}^{n} \sigma\left(v_{i}\right) \mathbf{d}\left(v_{i}\right)$. The importance of the existence of such an algorithm stems from the fact that, in general, quiver semi-stability requires one check a number of linear homogeneous inequalities that can grow exponentially.

In Lemma 8, we show that $\mathbf{D}_{Q}(V, \sigma)$ is the infimum of certain determinantal expressions where the infimum is taken over all positive definite matrices $Y_{j} \in$ $\mathbb{R}^{\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(w_{j}\right)}, j \in[m]$. We say that a quiver datum $(V, \sigma)$ is gaussian-extremisable if the infimum defining $\mathbf{D}_{Q}(V, \sigma)$ is attained for some positive definite matrices $Y_{j} \in$ $\mathbb{R}^{\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(w_{j}\right)}, j \in[m]$. If this is the case, we call such an $m$-tuple $\left(Y_{1}, \ldots, Y_{m}\right)$ a gaussian extremiser for $(V, \sigma)$.

One of our main goals in this paper is to find a constructive method for computing $\mathbf{D}_{Q}(V, \sigma)$, and gaussian extremisers whenever $(V, \sigma)$ is gaussian extremisable. To this end, we introduce the notion of a geometric quiver datum: we say that $(V, \sigma)$ is geometric if the corresponding operator $T_{V, \sigma}$ is doubly stochastic (see Definition 12). Consequently, the capacity of such a datum is always one (see [18, Proposition 2.8 and Corollary 3.4]). Geometric quiver data are also intimately related to the Kempf-Ness theorem on closed orbits in invariant theory.

Our next result gives a quiver invariant process that transforms an arbitrary quiver datum $(V, \sigma)$ with $\mathrm{D}_{Q}(V, \sigma)>0$ into a geometric one. In particular it leads to a character formula for $\mathbf{D}_{Q}(V, \sigma)$. To state this result, we need to introduce a few more concepts. The representation space of dimensional representations of $Q$ is the affine space $\operatorname{rep}(Q, \mathbf{d})=\prod_{a \in Q_{1}} \mathbb{R}^{\mathbf{d}(h a) \times \mathbf{d}(t a)}$. It is acted upon by the change of base group $G L(\mathbf{d})=\prod_{x \in Q_{0}} G L(\mathbf{d}(x), \mathbb{R})$ by simultaneous conjugation. The character of $\mathrm{GL}(\mathbf{d})$ induced by $\sigma$ is $\chi_{\sigma}: G L(\mathbf{d}) \rightarrow \mathbb{R}^{\times}=\mathbb{R} \backslash\{0\}, \chi_{\sigma}(A)=\prod_{x \in Q_{0}} \operatorname{det}(A(x))^{\sigma(x)}$ for all $A=(A(x))_{x \in Q_{0}} \in \mathrm{GL}(\mathbf{d})$. We denote by $\mathrm{GL}(\mathbf{d})_{\sigma}$ the kernel of $\chi_{\sigma}$.

Theorem 2. Let $Q$ be a bipartite quiver, $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ a dimension vector of $Q$, and $\sigma \in \mathbb{Z}^{Q_{0}}$ an integral weight of $Q$ orthogonal to d. Assume that $\sigma$ is positive on $Q_{0}^{+}$and negative on $Q_{0}^{-}$.

1. (Kempf-Ness theorem for real quiver representations) For a $\sigma$-semi-stable representation $V \in \operatorname{rep}(Q, \mathbf{d})$, consider the real algebraic variety

$$
\mathcal{G}_{\sigma}(V):=\{A \in \mathrm{GL}(\mathbf{d}) \mid(A \cdot V, \sigma) \text { is a geometric datum }\} .
$$

Then

$$
\mathcal{G}_{\sigma}(V) \neq \emptyset \Longleftrightarrow V \text { is } \sigma \text { - polystable. }
$$

2. (A character formula for capacity) Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a $\sigma$-semi-stable representation. Then there exists a $\sigma$-polystable representation $\widetilde{V}$ such that $\widetilde{V} \in \overline{\mathrm{GL}(\mathbf{d})_{\sigma} V}$. Furthermore, for any such $\widetilde{V}$, the following formula holds

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(\widetilde{V}, \sigma)=\chi_{\sigma}(A)^{2}, \forall A \in \mathcal{G}_{\sigma}(\widetilde{V})
$$

3. (Factorization of capacity) Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a representation such that

$$
V(a)=\left(\begin{array}{cc}
V_{1}(a) & X(a) \\
0 & V_{2}(a)
\end{array}\right), \forall a \in O_{1}
$$

where $V_{i} \in \operatorname{rep}\left(Q, \mathbf{d}_{i}\right), i \in\{1,2\}$, are representations of $Q$, and $X(a) \in$ $\mathbb{R}^{\mathbf{d}_{1}(h a) \times \mathbf{d}_{2}(t a)}, \forall a \in O_{1}$. If $\sigma \cdot \operatorname{dim} V_{1}=0$ then

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}\left(V_{1}, \sigma\right) \cdot \mathbf{D}_{Q}\left(V_{2}, \sigma\right)
$$

4. (Gaussian extremisers: existence) A quiver datum $(V, \sigma)$ with $\mathbf{D}_{Q}(V, \sigma)>0$ is gaussian-extremisable if and only if $V$ is $\sigma$-polystable. If this is the case then the gaussian extremisers of $(V, \sigma)$ are the $m$-tuples of matrices

$$
\left(A\left(w_{j}\right)^{T} \cdot A\left(w_{j}\right)\right)_{j \in[m]} \text { with } A \in \mathcal{G}_{\sigma}(V)
$$

5. (Gaussian extremisers: uniqueness) If a quiver datum $(V, \sigma)$ with $\mathbf{D}_{Q}(V, \sigma)>$ 0 has unique gaussian extremisers (up to scaling) then $V$ is $\sigma$-stable. Conversely if $V$ is $\sigma$-stable with a one-dimensional space of endomorphisms then ( $V, \sigma$ ) has unique gaussian extremisers (up to scaling).

In Theorem 22, we reformulate the results above in terms of BL constants for bipartite quivers. When $Q$ is the $m$-subspace quiver $\mathcal{Q}_{m}$, we recover the main results of Bennet-Carbery-Christ-Tao [4] on the classical BL constants with rational $m$-exponents.

On the computational side, the character formula above opens up the possibility of computing capacities (BL constants) and gaussian extremisers for quiver data via algebraic sampling algorithms (see e.g., [10]).

## 2 Brascamp-Lieb Operators and the Capacity of Ouiver Representations

Throughout, we work over the field $\mathbb{R}$ of real numbers and denote by $\mathbb{N}=\{0,1, \ldots\}$. For a positive integer $L$, we denote by $[L]=\{1, \ldots, L\}$.

A quiver $Q=\left(Q_{0}, Q_{1}, t, h\right)$ consists of two finite sets $Q_{0}$ (vertices) and $Q_{1}$ (arrows) together with two maps $t: Q_{1} \rightarrow Q_{0}$ (tail) and $h: Q_{1} \rightarrow Q_{0}$ (head). We represent $Q$ as a directed graph with set of vertices $O_{0}$ and directed edges $a: t a \rightarrow$ ha for every $a \in O_{1}$. Throughout we assume that our quivers are connected, meaning that the underlying graph of $Q$ is connected.

A representation of $Q$ is a family $V=(V(x), V(a))_{x \in Q_{0}, a \in Q_{1}}$ where $V(x)$ is a finitedimensional $\mathbb{R}$-vector space for every $x \in Q_{0}$, and $V(a): V(t a) \rightarrow V(h a)$ is a $\mathbb{R}$-linear map for every $a \in Q_{1}$. A subrepresentation $V^{\prime}$ of $V$, written as $V^{\prime} \leq V$, is a representation of $Q$ such that $V^{\prime}(x) \leq_{\mathbb{R}} V(x)$ for every $x \in Q_{0}$, and $V(a)\left(V^{\prime}(t a)\right) \subseteq V^{\prime}(h a)$ and $V^{\prime}(a)$ is the restriction of $V(a)$ to $V(t a)$ for every arrow $a \in Q_{1}$.

The dimension vector $\operatorname{dim} V \in \mathbb{N}^{Q_{0}}$ of a representation $V$ is defined by $\operatorname{dim} V(x)=$ $\operatorname{dim}_{\mathbb{R}} V(x)$ for all $x \in O_{0}$. By a dimension vector of $Q$, we simply mean a $\mathbb{Z}_{\geq 0}$-valued function on the set of vertices $Q_{0}$. For two vectors $\theta, \beta \in \mathbb{R}^{Q_{0}}$, we define $\theta \cdot \beta=$ $\sum_{x \in Q_{0}} \theta(x) \beta(x)$.

Let $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ be a dimension vector. The representation space of $\mathbf{d}$-dimensional representations of $Q$ is the affine space

$$
\operatorname{rep}(Q, \mathbf{d})=\prod_{a \in Q_{1}} \mathbb{R}^{\mathbf{d}(h a) \times \mathbf{d}(t a)}
$$

The change-of-base group $G L(\mathbf{d})=\prod_{x \in Q_{0}} G L(\mathbf{d}(x), \mathbb{R})$ acts on $\operatorname{rep}(Q, \mathbf{d})$ by simultaneous conjugation, that is, for $A=(A(x))_{x \in Q_{0}}$ and $V=(V(a))_{a \in Q_{1}}$, we have that

$$
(A \cdot V)(a)=A(h a) \cdot V(a) \cdot A(t a)^{-1}, \forall a \in O_{1}
$$

Note that there is a bijective correspondence between the isomorphism classes of representations of $Q$ of dimension vector $\mathbf{d}$ and the $G L(\mathbf{d})$-orbits in $\operatorname{rep}(Q, \mathbf{d})$.

From now on, we assume that $Q$ is bipartite. This means that $Q_{0}$ is the disjoint union of two subsets $Q_{0}^{+}$and $Q_{0}^{-}$, and all the arrows in $Q$ go from $Q_{0}^{+}$to $Q_{0}^{-}$. Write $Q_{0}^{+}=\left\{v_{1}, \ldots, v_{n}\right\}$ and $Q_{0}^{-}=\left\{w_{1}, \ldots, w_{m}\right\}$.

Let us fix an integral weight $\sigma \in \mathbb{Z}^{Q_{0}}$ such that $\sigma$ is positive on $Q_{0}^{+}$and negative on $Q_{0}^{-}$. Define

$$
\sigma_{+}\left(v_{i}\right)=\sigma\left(v_{i}\right), \forall i \in[n], \text { and } \sigma_{-}\left(w_{j}\right)=-\sigma\left(w_{j}\right), \forall j \in[m]
$$

Let $\mathbb{H}(\mathbf{d})=\left\{\sigma \in \mathbb{R}^{Q_{0}} \mid \sum_{x \in Q_{0}} \sigma(x) \mathbf{d}(x)=0\right\}$ be the space of real weights of $O$ orthogonal to $\mathbf{d}$, and let us assume that $\sigma \in \mathbb{H}(\mathbf{d})$. This is equivalent to

$$
N:=\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right) \mathbf{d}\left(v_{i}\right)=\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \mathbf{d}\left(w_{j}\right) .
$$

For $i \in[n]$ and $j \in[m]$, we denote the set of all arrows in $Q$ from $v_{i}$ to $w_{j}$ by $\mathcal{A}_{i, j}$. If there are no arrows from $v_{i}$ to $w_{j}$, we define $\mathcal{A}_{i, j}$ to be the set consisting of the symbol $\mathbf{0}_{i j}$.

Let $M:=\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right)$ and $M^{\prime}:=\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right)$. For each $j \in[m]$ and $i \in[n]$, define

$$
\mathcal{I}_{j}^{-}:=\left\{q \in \mathbb{Z} \mid \sum_{k=1}^{j-1} \sigma_{-}\left(w_{k}\right)<q \leq \sum_{k=1}^{j} \sigma_{-}\left(w_{k}\right)\right\}
$$

and

$$
\mathcal{I}_{i}^{+}:=\left\{r \in \mathbb{Z} \mid \sum_{k=1}^{i-1} \sigma_{+}\left(v_{k}\right)<r \leq \sum_{k=1}^{i} \sigma_{+}\left(v_{k}\right)\right\} .
$$

In what follows, we consider $M \times M^{\prime}$ block matrices of size $N \times N$ such that for any two indices $q \in \mathcal{I}_{j}^{-}$and $r \in \mathcal{I}_{i}^{+}$, the $(q, r)$-block-entry is a matrix of size $\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(v_{i}\right)$. Set

$$
\mathcal{S}:=\left\{(i, j, a, q, r) \mid i \in[n], j \in[m], a \in \mathcal{A}_{i, j}, q \in \mathcal{I}_{j}^{-}, r \in \mathcal{I}_{i}^{+}\right\} .
$$

Now, let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a d-dimensional representation of $Q$. For each $(i, j, a, q, r) \in \mathcal{S}$, let $V_{q, r}^{i, j, a}$ be the $M \times M^{\prime}$ block matrix whose $(q, r)$-block-entry is $V(a) \in$ $\mathbb{R}^{\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(v_{i}\right)}$, and all other entries are zero. The convention is that if $a=\mathbf{0}_{i j} \in \mathcal{A}_{i, j}$ then $V(a)$ is the zero matrix of size $\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(v_{i}\right)$; hence, if there are no arrows from $v_{i}$ to $w_{j}$ then $V_{q, r}^{i, j, a}$ is the zero matrix of size $N \times N$.

Remark 3. The $N \times N$ matrices $V_{q, r}^{i, j, a}$, where $(i, j, a, q, r) \in \mathcal{S}$ and $V \in \operatorname{rep}(Q, \mathbf{d})$, play a key role in the theory of semi-invariants of acyclic quivers. Specifically, let $t_{q, r}^{i, j, a}$, $(i, j, a, q, r) \in \mathcal{S}$, be indeterminate variables. Then, assuming that $K=\mathbb{C}$, the coefficients of the polynomial

$$
\operatorname{det}\left(\sum_{(i, j, a, q, r)} t_{q, r}^{i, j, a} V_{q, r}^{i, j, a}\right) \in K[\operatorname{rep}(Q, \mathbf{d})]\left[t_{q, r}^{i, j, a}:(i, j, a, q, r) \in \mathcal{S}\right]
$$

span the weight space of semi-invariants $\operatorname{SI}(Q, d)_{\sigma}$. For more details, see [16, Section 5] and the reference therein.

Inspired by [19, Construction 4.2], we now introduce BL operators for arbitrary quivers.

Definition 4. Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a d-dimensional representation of $Q$.

1. The $B L$ operator $T_{V, \sigma}$ associated to $(V, \sigma)$ is defined to be the completely positive operator with Kraus operators $V_{q, r}^{i, j, a},(i, j, a, q, r) \in \mathcal{S}$, that is,

$$
\begin{aligned}
T_{V, \sigma}: \mathbb{R}^{N \times N} & \rightarrow \mathbb{R}^{N \times N} \\
X & \rightarrow T_{V, \sigma}(X):=\sum_{(i, j, a, q, r)}\left(V_{q, r}^{i, j, a}\right)^{T} \cdot X \cdot V_{q, r}^{i, j, a} .
\end{aligned}
$$

2. The capacity $\mathbf{D}_{Q}(V, \sigma)$ of $(V, \sigma)$ is defined to be the capacity of $T_{V, \sigma}$, that is,

$$
\mathbf{D}_{Q}(V, \sigma):=\inf \left\{\operatorname{Det}\left(T_{V, \sigma}(X)\right) \mid X \in \mathcal{S}_{N}^{+}, \operatorname{Det}(X)=1\right\}
$$

(Here, for a given positive integer $d$, we denote by $\mathcal{S}_{d}^{+}$the set of all $d \times d$ (symmetric) positive definite real matrices.)

## Remark 5.

1. We point out that completely positive operators are usually defined over $\mathbb{C}$, and the infimum defining their capacity is taken over positive definite complex matrices. However, if $T$ is defined by real Kraus operators, then one can simply work with positive definite real matrices in the definition of the capacity of $T$ (see [19, Remark 2.7]).
2. Any completely positive operator $T$ with Kraus operators $A_{1}, \ldots, A_{l}$ can be viewed as a BL operator for the generalized Kronecker quiver with $l$ arrows, representation $V=\left(A_{1}, \ldots, A_{l}\right)$, and weight $\sigma=(1,-1)$. However, it is important to keep $O$ arbitrary and not simply reduce the considerations to generalized Kronecker quivers. Indeed, Theorem 1 allows us to interpret quiver semi-stability for arbitrary bipartite (and not just generalized Kronecker) quivers in terms of the positivity of the capacity of BL operators. As already mentioned before, this in turn leads to a deterministic polynomial time algorithm for checking whether a representation $V$ of a bipartite quiver is semi-stable with respect to an integral weight $\sigma$.
3. Completely positive operators whose Kraus operators look similar to our $V_{q, r}^{i, j, a}$ are also considered in [17, Section 3]. However, our definition of $T_{V, \sigma}$ is based on quiver invariant theoretic considerations, and the overall approach in this paper is different than that in loc. cit.

Remark 6. BL operators can be defined for quivers that are not necessarily bipartite. Specifically, let $Q=\left(Q_{0}, Q_{1}, t, h\right)$ be an arbitrary acyclic quiver and $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ a dimension vector. Let $Q_{0}^{+}=\left\{v_{1}, \ldots, v_{n}\right\}$ and $Q_{0}^{-}=\left\{w_{1}, \ldots, w_{m}\right\}$ be two disjoint subsets of $Q_{0}$, and let $\sigma \in \mathbb{Z}^{O_{0}} \cap \mathbb{H}(\mathbf{d})$ be an integral weight such that $\sigma$ is positive on $Q_{0}^{+}$, negative on $Q_{0}^{-}$, and zero elsewhere.

Let $Q^{ \pm}$be the bipartite quiver with set of vertices $Q_{0}^{+} \cup Q_{0}^{-}$. For every oriented path $p$ in $Q$ from $v_{i}$ to $w_{j}$, we define an arrow $a_{p}$ in $Q^{ \pm}$from $v_{i}$ to $w_{j}$. Given a representation $V$ of $Q$, let $V^{ \pm}$be the representation of $Q^{ \pm}$defined by

- $V^{ \pm}\left(v_{i}\right)=V\left(v_{i}\right), V^{ \pm}\left(w_{j}\right)=V\left(w_{j}\right)$ for all $i \in[n], j \in[m]$, and
- $V^{ \pm}\left(a_{p}\right)=V(p)$ for every arrow $a_{p}$ in $Q^{ \pm}$.

We then simply define $T_{V, \sigma}:=T_{V^{ \pm}, \sigma}$, and $\mathbf{D}_{Q}(V, \sigma):=\mathbf{D}_{Q^{ \pm}}\left(V^{ \pm}, \sigma\right)$.

To prove our first Theorem 1, we require the following very useful general criterion addressing the positivity of the capacity of a completely positive operator.

Lemma 7. ([19, Corollary 3.15]) Let $T: \mathbb{R}^{N \times N} \rightarrow \mathbb{R}^{N \times N}$ be a completely positive operator. Then $\mathbf{D}(T)>0$ if and only if

$$
\operatorname{rank}(X) \leq \operatorname{rank} T^{*}(X), \forall X \succeq 0
$$

We point out that the proof below is an adaptation of that of [19, Lemma 4.4] to our general quiver set-up. Nonetheless, we include it for completeness and convenience of the reader.

Proof of Theorem 1. We will prove that $\mathbf{D}_{Q}(V, \sigma)>0$ if and only if

$$
\begin{equation*}
\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right) \operatorname{dim} V^{\prime}\left(v_{i}\right) \leq \sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \operatorname{dim}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} V(a)\left(V^{\prime}\left(v_{i}\right)\right)\right) \tag{2}
\end{equation*}
$$

for all subspaces $V^{\prime}\left(V_{i}\right) \leq \mathbb{R}^{\mathbf{d}\left(V_{i}\right)}, \forall i \in[n]$. The latter is easily seen to be equivalent to $V$ being $\sigma$-semi-stable.

We know from Lemma 7 that

$$
\mathbf{D}(V, \sigma)>0 \Longleftrightarrow \operatorname{rank}(X) \leq \operatorname{rank}\left(T_{V, \sigma}^{*}(X)\right), \forall N \times N \text { matrices } X \succeq 0
$$

By definition,

$$
T_{V, \sigma}^{*}(X)=\sum_{(i, j, a, q, r)} V_{q, r}^{i, j, a} \cdot X \cdot\left(V_{q, r}^{i, j, a}\right)^{T}, \forall X \in \mathbb{R}^{N \times N}
$$

Viewing each $N \times N$ matrix $X$ as an $M^{\prime} \times M^{\prime}$ block matrix, we get that for each $(i, j, a, q, r) \in$ $\mathcal{S}$, the matrix

$$
V_{q, r}^{i, j, a} \cdot X \cdot\left(V_{q, r}^{i, j, a}\right)^{T}
$$

has an $M \times M$ block matrix structure whose $(q, q)$-block entry is

$$
V(a) \cdot X_{r r} \cdot(V(a))^{T}
$$

and all other blocks are zero. So, $T_{V, \sigma}^{*}(X)$ is the $M \times M$ block-diagonal matrix whose $(q, q)$-block-diagonal entry is

$$
\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} V(a)\left(\sum_{r \in \mathcal{I}_{i}^{+}} X_{r r}\right) V(a)^{T}
$$

for all $q \in \mathcal{I}_{j}^{-}$and $j \in[m]$. It now follows that

$$
\begin{array}{r}
\operatorname{rank}(X) \leq \operatorname{rank}\left(T_{V, \sigma}^{*}(X)\right), \forall N \times N \text { matrices } X \succeq 0 \\
\hat{\Downarrow} \\
\sum_{i=1}^{n} \sum_{r \in \mathcal{I}_{i}^{+}} \operatorname{rank}\left(X_{r}\right) \leq \sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \operatorname{rank}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} V(a)\left(\sum_{r \in \mathcal{I}_{i}^{+}} X_{r}\right) V(a)^{T}\right)
\end{array}
$$

for all positive semi-definite matrices $X_{r} \in \mathbb{R}^{\mathbf{d}\left(v_{i}\right) \times \mathbf{d}\left(v_{i}\right)}$ with $r \in \mathcal{I}_{i}^{+}$and $i \in[n]$.
$(\Longrightarrow)$ Let us assume that the linear homogeneous inequalities ( $\star$ ) hold for all positive semi-definite matrices $X_{r} \in \mathbb{R}^{\mathbf{d}\left(v_{i}\right) \times \mathbf{d}\left(v_{i}\right)}$ with $r \in \mathcal{I}_{i}^{+}$and $i \in\{1, \ldots, n\}$.

Let $V^{\prime}\left(V_{i}\right) \leq \mathbb{R}^{\mathbf{d}\left(v_{i}\right)}, i \in[n]$, be arbitrary subspaces. Choose an orthonormal basis $\left\{u_{1}^{i}, \ldots, u_{\mathbf{d}^{\prime}(i)}^{i}\right\}$ for each $V^{\prime}\left(v_{i}\right)$ and set

$$
X_{r}=\sum_{l=1}^{\mathrm{d}^{\prime}\left(v_{i}\right)} u_{l}^{i} \cdot\left(u_{l}^{i}\right)^{T}
$$

for every $r \in \mathcal{I}_{i}^{+}$. Plugging these matrices into ( $\star$ ), we get

$$
\begin{equation*}
\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right) \cdot \operatorname{dim} V^{\prime}\left(v_{i}\right) \leq \sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \operatorname{rank}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} \sum_{r, l} V(a) u_{l}^{i}\left(V(a) u_{l}^{i}\right)^{T}\right) . \tag{3}
\end{equation*}
$$

But each rank $\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} \sum_{r, l} V(a) u_{l}^{i}\left(V(a) u_{l}^{i}\right)^{T}\right)$ equals the dimension of the space spanned by the vectors $V(a) u_{l}^{i}$, that is,

$$
\begin{equation*}
\operatorname{rank}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} \sum_{r, l} V(a) u_{l}^{i}\left(V(a) u_{l}^{i}\right)^{T}\right)=\operatorname{dim}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} V(a)\left(V^{\prime}\left(v_{i}\right)\right)\right) \tag{4}
\end{equation*}
$$

It now follows from (3) and (4) that

$$
\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right) \operatorname{dim} V^{\prime}\left(v_{i}\right) \leq \sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \operatorname{dim}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i j}} V(a)\left(V^{\prime}\left(v_{i}\right)\right)\right)
$$

$(\Longleftarrow)$ Let $X_{r} \in \mathbb{R}^{\mathbf{d}\left(v_{i}\right) \times \mathbf{d}\left(v_{i}\right)}, r \in \mathcal{I}_{i}^{+}, i \in\{1, \ldots, n\}$, be arbitrary positive semi-definite matrices. For each such $r$ and $i$, let $\left\{u_{1}^{i, r}, \ldots, u_{d_{i, r}}^{i, r}\right\}$ be an orthonormal set of vectors in
$\mathbb{R}^{\mathrm{d}\left(\mathrm{V}_{i}\right)}$ such that

$$
X_{r}=\sum_{l=1}^{\mathbf{d}_{i, r}} \lambda_{l}^{i, r} u_{l}^{i, r} \cdot\left(u_{l}^{i, r}\right)^{T}
$$

with the $\lambda_{l}^{i, r}>0$; in particular, $\operatorname{rank}\left(X_{r}\right)=\mathbf{d}_{i, r}$. Now, define

$$
V^{\prime}\left(v_{i}\right)=\operatorname{Span}\left(\sqrt{\lambda_{l}^{i, r}} \cdot u_{l}^{i, r} \mid r \in \mathcal{I}_{i}^{+}, 1 \leq l \leq \mathbf{d}_{i, r}\right) \leq \mathbb{R}^{\mathbf{d}\left(v_{i}\right)} .
$$

Working with these subspaces in (2), we get that ( $\star$ ) holds all positive semi-definite matrices $X_{r}$. In other words, $\mathbf{D}\left(T_{V, \sigma}\right)>0$.

## 3 Brascamp-Lieb Constants From Capacity of Ouiver Representations

Let $Q=\left(Q_{0}, Q_{1}, t, h\right)$ be a bipartite quiver with set of source vertices $Q_{0}^{+}=\left\{v_{1}, \ldots, v_{n}\right\}$ and set of sink vertices $Q_{0}^{-}=\left\{w_{1}, \ldots, w_{m}\right\}$. Let $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ be a dimension vector of $Q$ and $\sigma \in \mathbb{H}(\mathbf{d}) \cap \mathbb{Z}^{Q_{0}}$ a weight such that $\sigma$ is positive on $Q_{0}^{+}$and negative on $Q_{0}^{-}$. Recall the notation from Section 2:

- $\sigma_{+}\left(v_{i}\right)=\sigma\left(v_{i}\right), \forall i \in[n]$ and $\sigma_{-}\left(w_{j}\right)=-\sigma\left(w_{j}\right), \forall j \in[m] ;$
- $N=\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right) \mathbf{d}\left(v_{i}\right)=\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \mathbf{d}\left(w_{j}\right) ;$
- $\mathcal{A}_{i, j}$ is the set of arrows from $v_{i}$ to $w_{j}$ in $Q$ for all $i \in\{1, \ldots, n\}$ and $j \in\{1, \ldots, m\} ;$
- $M:=\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right)$, and $M^{\prime}:=\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right)$.

For each $j \in\{1, \ldots, m\}$ and $i \in\{1, \ldots, n\}$, we furthermore define

$$
\mathcal{I}_{j}^{-}:=\left\{q \in \mathbb{Z} \mid \sum_{k=1}^{j-1} \sigma_{-}\left(w_{k}\right)<q \leq \sum_{k=1}^{j} \sigma_{-}\left(w_{k}\right)\right\}
$$

and

$$
\mathcal{I}_{i}^{+}:=\left\{r \in \mathbb{Z} \mid \sum_{k=1}^{i-1} \sigma_{+}\left(v_{k}\right)<r \leq \sum_{k=1}^{i} \sigma_{+}\left(v_{k}\right)\right\}
$$

In Lemma 8 below we provide a more explicit formula for the capacity of a quiver datum $(V, \sigma)$ that will lead us to the definition of the BL constant associated to $(V, \sigma)$. For this, we recall the following well-known facts. Let $X$ be a positive semi-definite $N \times N$
matrix, viewed as an $M \times M$ block matrix. For each $j \in[m]$ and $q \in \mathcal{I}_{j}^{-}$, denote by $X_{q q}$ the $(q, q)$-block-diagonal entry of $X$; it is of size $\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(w_{j}\right)$. Then we have that

$$
\begin{equation*}
\operatorname{det}(X) \leq \prod_{j=1}^{m} \prod_{q \in \mathcal{I}_{j}^{-}} \operatorname{det}\left(X_{q q}\right) . \tag{5}
\end{equation*}
$$

Next, for any $j \in\{1, \ldots, m\}$, set

$$
Y_{j}:=\frac{\sum_{q \in \mathcal{I}_{j}^{-}} X_{q q}}{\sigma_{-}\left(w_{j}\right)} .
$$

Then a generalization of Hadamard's inequality yields

$$
\begin{equation*}
\prod \operatorname{det}\left(X_{q q}\right) \leq \operatorname{det}\left(Y_{j}\right)^{\sigma_{-}\left(W_{j}\right)} \tag{6}
\end{equation*}
$$

We are now ready to prove the following formula for $\mathbf{D}_{Q}(V, \sigma)$ for $V \in \operatorname{rep}(Q, \mathbf{d})$.

Lemma 8. Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a representation of $Q$. Then

$$
\begin{aligned}
& \mathbf{D}_{Q}(V, \sigma)= \\
& =\inf \left\{\left.\frac{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)^{\sigma_{+}\left(V_{i}\right)}}{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{\sigma_{-}\left(w_{j}\right)}} \right\rvert\, Y_{j} \in \mathcal{S}_{\mathrm{d}\left(w_{j}\right)}^{+}\right\} .
\end{aligned}
$$

Furthermore, if the weight $\sigma$ is so that $\sigma_{+}\left(V_{1}\right)=\ldots=\sigma_{+}\left(v_{n}\right)=\omega>0$, then

$$
\mathbf{D}_{Q}(V, \sigma)=\frac{1}{\omega^{-N}} \cdot\left(\inf \left\{\left.\frac{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} p_{j}\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)}{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{p_{j}}} \right\rvert\, Y_{j} \in \mathcal{S}_{\mathrm{d}\left(w_{j}\right)}^{+}\right\}\right)^{\omega}
$$

where $p_{j}=-\frac{\sigma\left(w_{j}\right)}{\omega}$ for all $j \in[m]$.

## Proof. We have that

$$
\begin{aligned}
& \quad \mathbf{D}_{Q}(V, \sigma)=\inf \left\{\operatorname{det}\left(T_{V, \sigma}(X)\right) \mid X \in \mathcal{S}_{N}^{+}, \operatorname{det}(X)=1\right\} \\
& =\inf \left\{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sum_{a \in \mathcal{A}_{i, j}} V(a)^{T}\left(\sum_{q \in \mathcal{I}_{j}^{-}} X_{q q}\right) V(a)\right)^{\sigma_{+}\left(V_{i}\right)} \mid X \in \mathcal{S}_{N}^{+}, \operatorname{det}(X)=1\right\} \\
& \stackrel{(i i i)}{=} \inf \left\{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sum_{a \in \mathcal{A}_{i, j}} V(a)^{T}\left(\sum_{q \in \mathcal{I}_{j}^{-}} X_{q}\right) V(a)\right)^{\sigma_{+}\left(V_{i}\right)} \mid X_{q} \in \mathcal{S}_{\mathbf{d}\left(w_{j}\right)}^{+} \prod_{j=1}^{m} \prod_{q \in \mathcal{I}_{j}^{-}} \operatorname{det}\left(X_{q}\right)=1\right\} \\
& \stackrel{(i v)}{=} \inf \left\{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)^{\sigma_{+}\left(V_{i}\right)} \mid Y_{j} \in \mathcal{S}_{\mathbf{d}\left(w_{j}\right)}^{+} \prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{\sigma_{-}\left(w_{j}\right)}=1\right\} \\
& \stackrel{(v)}{=} \inf \left\{\left.\frac{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)^{\sigma_{+}\left(V_{i}\right)} \mid}{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{\sigma_{-}\left(w_{j}\right)}} \right\rvert\, Y_{j} \in \mathcal{S}_{\mathbf{d}\left(w_{j}\right)}^{+}\right\} .
\end{aligned}
$$

To prove the 3rd equality above, one can simply use (5). Indeed, it is clear that the infimum displayed on the 2nd line above is less than or equal to that on the 3rd line. To prove the reverse inequality, let $X$ be a positive definite $N \times N$ real matrix with $\operatorname{det}(X)=1$ and let us denote by $X_{q}$ the block-diagonal entries of $X$. Then, by (5), we have that

$$
1=\operatorname{det}(X) \leq C:=\prod_{j=1}^{m} \prod_{q \in \mathcal{I}_{j}^{-}} \operatorname{det}\left(X_{q}\right)
$$

Setting $\widetilde{X}_{q}=\frac{1}{\sqrt[N]{C}} X_{q}$, we get that $\prod_{j=1}^{m} \prod_{q \in \mathcal{I}_{j}^{-}} \operatorname{det}\left(\widetilde{X}_{q}\right)=1$, and

$$
\begin{aligned}
\prod_{i=1}^{n} \operatorname{det} & \left(\sum_{j=1}^{m} \sum_{a \in \mathcal{A}_{i, j}} V(a)^{T}\left(\sum_{q \in \mathcal{I}_{j}^{-}} \tilde{X}_{q}\right) V(a)\right)^{\sigma_{+}\left(V_{i}\right)}= \\
= & \frac{1}{C} \prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sum_{a \in \mathcal{A}_{i, j}} V(a)^{T}\left(\sum_{q \in \mathcal{I}_{j}^{-}} X_{q}\right) V(a)\right)^{\sigma_{+}\left(V_{i}\right)}
\end{aligned}
$$

This now gives get the reverse inequality, proving the 3rd equality above. For (iv), one can simply use the generalized Hadamard's inequality (6). For (v), simply work with
$\frac{Y_{j}}{\sqrt[N]{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{\sigma-\left(w_{j}\right)}}}, j \in\{1, \ldots, m\}$, in the line above, where $Y_{j} \in \operatorname{Mat}_{\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(w_{j}\right)}, j \in[m]$, are arbitrary positive definite matrices.

The formula for $\mathbf{D}_{Q}(V, \sigma)$ when $\sigma_{+}$is constant follows immediately from the computations above.

Let $\chi_{\sigma}: \operatorname{GL}(\mathbf{d}) \rightarrow \mathbb{R}^{\times}$be the character induced by $\sigma$, that is, $\chi_{\sigma}(A)=$ $\prod_{x \in Q_{0}} \operatorname{det}(A(x))^{\sigma(x)}$ for all $A=(A(x))_{x \in Q_{0}} \in \mathrm{GL}(\mathbf{d})$, and denote its kernel by GL(d) ${ }_{\sigma}$. As a consequence of the lemma above, we get the following formula for the capacity along GL(d)-orbits.

Corollary 9. Let $V \in \operatorname{rep}(Q, \mathbf{d})$ and $A=(A(x))_{x \in Q_{0}} \in \operatorname{GL}(\mathbf{d})$. Then

$$
\mathbf{D}_{Q}(V, \sigma)=\left(\chi_{\sigma}(A)\right)^{2} \cdot \mathbf{D}_{Q}(A \cdot V, \sigma)
$$

In particular, if $A \in \mathrm{GL}(\mathbf{d})_{\sigma}$ then

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(A \cdot V, \sigma),
$$

that is, the capacity is constant along $\mathrm{GL}(\mathbf{d})_{\sigma}$-orbits.

We are now ready to define BL constants for bipartite quivers. This definition is inspired by Lieb's remarkable determinantal formula [22] for the classical BL constants and Lemma 8.

Definition 10. (BL constants for quiver datum) Let $V \in \operatorname{rep}(~ Q, \mathbf{d})$ be a d-dimensional representation and let $\mathbf{p}=\left(p_{1}, \ldots, p_{m}\right) \in \mathbb{Q}_{>0}^{m}$ be an $m$-tuple of positive rational numbers such that $\sum_{i=1}^{n} \mathbf{d}\left(v_{i}\right)=\sum_{j=1}^{m} p_{j} \mathbf{d}\left(w_{j}\right)$. We define the $B L$ constant $\mathrm{BL}_{Q}(V, \mathbf{p})$ associated to ( $V, \mathbf{p}$ ) by

$$
\begin{equation*}
\mathrm{BL}_{Q}(V, \mathbf{p})=\sup \left\{\left.\left(\frac{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{p_{j}}}{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} p_{j}\left(\sum_{a \in \mathcal{A}_{i j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)}\right)^{\frac{1}{2}} \right\rvert\, Y_{j} \in \mathcal{S}_{\mathbf{d}\left(w_{j}\right)}^{+}\right\} \tag{7}
\end{equation*}
$$

(When computing the supremum above, the convention is that $\frac{1}{0}$ is $\infty$.)

## Remark 11.

(a) Using Lieb's formula (see [22]), we obtain that $\mathrm{BL}_{\mathcal{Q}_{m}}(V, \mathbf{p})$, where $\mathcal{Q}_{m}$ is the $m$-subspace quiver, is precisely the classical BL constant BL(V,p).
(b) Keep the same notation as in the definition above. Let $\sigma_{p}$ be the integral weight of $Q$ defined by $\sigma_{\mathbf{p}}\left(x_{i}\right)=\omega$ for all $i \in[n]$ and $\sigma_{\mathbf{p}}\left(w_{j}\right)=-\omega \cdot p_{j}$ for all $j \in[m]$. Then, according to Lemma 8, we have that

$$
\mathrm{BL}_{Q}(V, \mathbf{p})= \begin{cases}\frac{1}{\sqrt[2 \omega]{\omega^{-N} \mathbf{D}_{Q}\left(V, \sigma_{\mathbf{p}}\right)}} & \text { if } \mathbf{D}_{Q}\left(V, \sigma_{\mathbf{p}}\right)>0  \tag{8}\\ \infty & \text { if } \mathbf{D}_{Q}\left(V, \sigma_{\mathbf{p}}\right)=0\end{cases}
$$

(c) According to Theorem 1, $\mathrm{BL}_{Q}(V, \mathbf{p})<\infty$ if and only if $\sum_{i=1}^{n} \mathbf{d}\left(v_{i}\right)=$ $\sum_{j=1}^{m} p_{j} \mathbf{d}\left(w_{j}\right)$ and

$$
\begin{equation*}
\sum_{i=1}^{n} \operatorname{dim} V^{\prime}\left(v_{i}\right) \leq \sum_{j=1}^{m} p_{j} \operatorname{dim}\left(\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i j}} V(a)\left(V^{\prime}\left(v_{i}\right)\right)\right) \tag{9}
\end{equation*}
$$

for all subspaces $V^{\prime}\left(v_{i}\right) \leq \mathbb{R}^{\mathbf{d}\left(v_{i}\right)}, \forall i \in[n]$. In particular, when $Q$ is the $m$ subspace quiver, this recovers Bennet-Carbery-Christ-Tao's finitness result from [4, Theorem 1.13].

## 4 Geometric quiver data

Let $Q=\left(Q_{0}, Q_{1}, t, h\right)$ be a bipartite quiver with set of source vertices $Q_{0}^{+}=\left\{v_{1}, \ldots, v_{n}\right\}$, and set of sink vertices $Q_{0}^{-}=\left\{w_{1}, \ldots, w_{m}\right\}$. Let $\mathcal{A}_{i, j}$ be the set of all arrows from $v_{i}$ to $w_{j}$ for all $i \in[n]$ and $j \in[m]$.

Let $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ be a dimension vector and let $\sigma \in \mathbb{H}(\mathbf{d}) \cap \mathbb{Z}^{O_{0}}$ be a weight orthogonal to $\mathbf{d}$ such that $\sigma$ is positive on $Q_{0}^{+}$and negative on $Q_{0}^{-}$. Recall that $\sigma_{+}\left(V_{i}\right)=\sigma\left(V_{i}\right), \forall i \in$ $\{1, \ldots, n\}$, and $\sigma_{-}\left(w_{j}\right)=-\sigma\left(w_{j}\right), \forall j \in\{1, \ldots, m\}$.

Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a d-dimensional representation and $T_{V, \sigma}$ the BL operator associated to $(V, \sigma)$. Recall that $T_{V, \sigma}$ is a doubly stochastic operator if $T_{V, \sigma}(\mathbf{I})=T_{V, \sigma}^{*}(\mathbf{I})=$ I , which is equivalent to

$$
\begin{equation*}
\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right) \sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot V(a)=\mathbf{I}_{\mathbf{d}\left(V_{i}\right)}, \forall i \in[n] \tag{10}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{i=1}^{n} \sigma_{+}\left(v_{i}\right) \sum_{a \in \mathcal{A}_{i, j}} V(a) \cdot V(a)^{T}=\mathrm{I}_{\mathrm{d}\left(w_{j}\right)}, \forall j \in[m] \tag{11}
\end{equation*}
$$

Definition 12. We call $(V, \sigma)$ a geometric quiver datum if $V$ satisfies the matrix equations (10) and (11).

One of the advantages of working with geometric quiver data is that their capacity is known to be one (see [18, Proposition 2.8 and Lemma 3.4]), that is, for a geometric datum ( $V, \sigma$ ), we have that

$$
\mathbf{D}_{Q}(V, \sigma)=1
$$

### 4.1 A character formula for the capacity of quiver data

Our goal in this section is to understand the matrix equations (10) and (11) in the context of quiver invariant theory. This will lead us to a character formula for the capacity of quiver data.

Recall that the affine space $\operatorname{rep}(Q, \mathbf{d})$ of $\mathbf{d}$-dimensional representations of $Q$ is acted upon by the change-of-base group $\mathrm{GL}(\mathbf{d})=\prod_{x \in Q_{0}} \mathrm{GL}(\mathbf{d}(x), \mathbb{R})$ by simultaneous conjugation. The character induced by $\sigma$ is denoted by $\chi_{\sigma}: G L(d) \rightarrow \mathbb{R}^{\times}$and its kernel is denoted by GL(d) ${ }_{\sigma}$.

## Theorem 13.

(i) For a $\sigma$-semi-stable representation $V \in \operatorname{rep}(Q, \mathbf{d})$, consider the real algebraic variety

$$
\mathcal{G}_{\sigma}(V):=\{A \in \mathrm{GL}(\mathbf{d}) \mid(A \cdot V, \sigma) \text { is a geometric quiver datum }\} .
$$

Then

$$
\mathcal{G}_{\sigma}(V) \neq \emptyset \Longleftrightarrow V \text { is } \sigma \text { - polystable. }
$$

(ii) For a $\sigma$-semi-stable representation $V \in \operatorname{rep}(Q, \mathbf{d})$, there exists a $\sigma$-polystable representation $\widetilde{V}$ such that $\widetilde{V} \in \overline{\mathrm{GL}(\mathbf{d})_{\sigma} V}$. Furthermore, for any such $\widetilde{V}$, the
following formula holds:

$$
\begin{equation*}
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(\widetilde{V}, \sigma)=\chi_{\sigma}(A)^{2}, \forall A \in \mathcal{G}_{\sigma}(\tilde{V}) \tag{12}
\end{equation*}
$$

To prove this theorem, we require the following important result. It has been proved by King [21] over the field of complex numbers. Here, we explain how to prove it over the real numbers.

Proposition 14. Let $Q$ be a bipartite quiver, $\mathbf{d} \in \mathbb{N}^{Q_{0}}$ a dimension vector, and $\sigma \in \mathbb{Z}^{Q_{0}}$ an integral weight of $Q$ such that $\sigma \cdot \mathbf{d}=0$. Consider the action of $\operatorname{GL}(\mathbf{d})$ on $\operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}$ given by

$$
A \cdot(V, z)=\left(A \cdot V, \chi_{\sigma}(A) z\right), \forall A \in \mathrm{GL}(\mathbf{d}),(V, z) \in \operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}
$$

For a $\sigma$-semi-stable representation $W \in \operatorname{rep}(Q, \mathbf{d})$, the following statements are equivalent:
(1) $W$ is $\sigma$-polystable;
(2) the $\mathrm{GL}(\mathbf{d})_{\sigma}$-orbit of $W$ is closed in $\operatorname{rep}(Q, \mathbf{d})$;
(3) the $\mathrm{GL}(\mathbf{d})$-orbit of $(W, 1)$ is closed in $\operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}$;
(4) there exists a representation $W^{\prime} \in \mathrm{GL}(\mathbf{d}) W$ such that

$$
\begin{align*}
& \sum_{j=1}^{m} \sum_{a \in \mathcal{A}_{i j}} W^{\prime}(a)^{T} \cdot W^{\prime}(a)=\sigma_{+}\left(v_{i}\right) \mathbf{I}_{\mathbf{d}\left(v_{i}\right)}, \forall i \in[n]  \tag{13}\\
& \sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} W^{\prime}(a) \cdot W^{\prime}(a)^{T}=\sigma_{-}\left(w_{j}\right) \mathbf{I}_{\mathbf{d}\left(w_{j}\right)}, \forall j \in[m] . \tag{14}
\end{align*}
$$

Proof. Over the field of complex numbers, the equivalence of (2) and (3) follows from King's work in [21]. We also know that for rational representations of reductive groups (defined over $\mathbb{R}$ ), the orbit of a point (defined over $\mathbb{R}$ ) is closed over $\mathbb{R}$ if and only if it is closed over $\mathbb{C}$. This is a general result due to Birkes [8, Corollary 5.3] and Borel and Harish-Chandra [7, Proposition 2.3]. Consequently, we get the equivalence $(2) \Longleftrightarrow$ (3).

Next, let us prove that $(1) \Longrightarrow$ (3). For a $\sigma$-semi-stable representation $W$ if $W$ is $\sigma$-polystable then so is $W_{\mathbb{C}}$ where $W_{\mathbb{C}}$ is the base change of $W$ to $\mathbb{C}$ (see [20, Proposition 2.4 and Remark 2.5]). The latter is equivalent to the orbit of ( $W_{\mathbb{C}}, 1$ ) under
$G:=\prod_{x \in Q_{0}} \operatorname{GL}(\mathbf{d}(x), \mathbb{C})$ being closed in $X:=\prod_{a \in Q_{1}} \operatorname{Mat}_{\mathbf{d}(h a) \times \mathbf{d}(t a)}(\mathbb{C}) \times \mathbb{C}$ (see [21]). As mentioned above, this is further equivalent to (3). Thus we get that (1) implies (3).

Now, let us check that $(2) \Longrightarrow(1)$. Since $W$ is $\sigma$-semi-stable, there exists a $\sigma$ polystable representation lying in the closure of $\mathrm{GL}(\alpha)_{\sigma} W$. Indeed, such a polystable representation can be taken to be the associated graded representation corresponding to a Jordan-Hölder filtration of $W$ in the category rep $(Q)_{\sigma}^{s s}$ (for more details, see also Theorem 13(ii)). So, assuming (2), this $\sigma$-polystable representation belongs to $\mathrm{GL}(\mathbf{d})_{\sigma} W$; in particular, it is isomorphic to $W$, and hence $W$ is $\sigma$-polystable.

It remains to show that $(3) \Longleftrightarrow(4)$. For this, consider the above action of $\mathrm{GL}(\mathbf{d})$ on $\operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}$ at the level of Lie algebras:

$$
A \cdot(V, z)=\left((A(h a) \cdot V(a)-V(a) \cdot A(t a))_{a \in Q_{1}}\left(\sum_{x \in Q_{0}} \sigma(x) \operatorname{Tr}(A(x))\right) \cdot z\right)
$$

for every $A=(A(x))_{x \in Q_{0}} \in \mathbb{R}^{\mathbf{d} \times \mathbf{d}}:=\prod_{x \in Q_{0}} \mathbb{R}^{\mathbf{d}(x) \times \mathbf{d}(x)}, V=(V(a))_{a \in Q_{1}} \in \operatorname{rep}(Q, \mathbf{d})$, and $z \in \mathbb{R}$. We equip $\operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}$ with the inner product $\langle-,-\rangle$ induced from the natural inner product $\langle Y, Z\rangle=\operatorname{Tr}\left(Y \cdot Z^{T}\right)$ on each $\mathbb{R}^{\mathbf{d}(h a) \times \mathbf{d}(t a)}, a \in Q_{1}$. In what follows, we say that $(V, z) \in \operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}$ is minimal (or critical) if

$$
\langle A \cdot(V, z),(V, z)\rangle=0, \forall A \in \mathbb{R}^{\mathbf{d} \times \mathbf{d}},
$$

which is equivalent to

$$
\sum_{a \in Q_{1}, t a=x} V(a)^{T} V(a)-\sum_{a \in Q_{1}, h a=x} V(a) V(a)^{T}=\sigma(x) z^{2} \mathbf{I}_{\mathrm{d}(x)}, \forall x \in O_{0} .
$$

According to the Kempf-Ness theory of minimal vectors over $\mathbb{R}$ (see e.g., [23, Theorem 3.28] or [9, Theorem 1.1]), the GL(d)-orbit of ( $W, 1$ ) is closed in $\operatorname{rep}(~ Q, \mathbf{d}) \times \mathbb{R}$ if and only if there exists $A \in \mathrm{GL}(\mathbf{d})$ such that $A \cdot(W, 1)=\left(A \cdot W, \chi_{\sigma}(A)\right)$ is minimal. It is immediate to see that for an $A \in \mathrm{GL}(\mathbf{d}),\left(A \cdot W, \chi_{\sigma}(A)\right)$ is minimal if and only if $W^{\prime}$ satisfies the matrix equations (13) and (14) where $W^{\prime}=A^{\prime} \cdot W \in \operatorname{GL}(\mathbf{d}) W$ and $A^{\prime}=$ $\left(\left|\chi_{\sigma}(A)\right|^{-\frac{1}{2}} \cdot A(X)\right)_{x \in Q_{0}} \in \mathrm{GL}(\mathbf{d})$.

Remark 15. We point out that Proposition 14 holds for arbitrary quivers. Specifically, let $Q$ be a connected quiver (not necessarily bipartite), $\mathbf{d} \in \mathbb{Z}_{\geq 0}^{O_{0}}$ a dimension vector, and $\sigma \in \mathbb{Z}^{Q_{0}}$ an integral weight such that $\sigma \cdot \mathbf{d}=0$. Let $W \in \operatorname{rep}(Q, \mathbf{d})$ be a $\sigma$-semi-stable
representation of $Q$. Then the proof above simply shows that the following statements are equivalent:
(1) $W$ is $\sigma$-polystable;
(2) the $\mathrm{GL}(\mathbf{d})_{\sigma}$-orbit of $W$ is closed in $\operatorname{rep}(Q, \mathbf{d})$;
(3) the $\mathrm{GL}(\mathbf{d})$-orbit of $(W, 1)$ is closed in $\operatorname{rep}(Q, \mathbf{d}) \times \mathbb{R}$;
(4) there exists a representation $W^{\prime} \in \mathrm{GL}(\mathbf{d}) W$ such that

$$
\sum_{a \in Q_{1}, t a=x} W^{\prime}(a)^{T} \cdot W^{\prime}(a)-\sum_{a \in Q_{1}, h a=x} W^{\prime}(a) \cdot W^{\prime}(a)^{T}=\sigma(x) \mathbf{I}_{\mathbf{d}(x)}, \forall x \in Q_{0}
$$

We are now ready to prove Theorem 13.

Proof of Theorem 13. (i) Let $V \in \operatorname{rep}(Q, \mathrm{~d})$ be a $\sigma$-semi-stable representation. Define $W \in \operatorname{rep}(Q, \mathbf{d})$ by $W(a):=\sqrt{\sigma_{+}(t a) \sigma_{-}(h a)} \cdot V(a)$ for every $a \in Q_{1}$. Furthermore, we can now see that $\mathcal{G}_{\sigma}(V) \neq \emptyset$ if and only if there exists an $A \in G L(\mathbf{d})$ such that $A \cdot W$ satisfies (13) and (14). Via Proposition 14, this is further equivalent to $W$, and hence $V$, being $\sigma$-polystable.
(ii) Since $V$ is $\sigma$-semi-stable, $V$ has a Jordan-Hölder filtration in rep $(Q)_{\sigma}^{s S}$. After choosing a basis for each $V(x)=\mathbb{R}^{\mathrm{d}(x)}$ compatible with this filtration, we can construct a 1-psg $\lambda^{\prime} \in X_{*}\left(\mathrm{GL}(\mathbf{d})_{\sigma}\right)$ and $h \in \mathrm{GL}(\mathbf{d})$ such that $\lim _{t \rightarrow 0} \lambda^{\prime}(t)(h \cdot V)$ exists and is isomorphic to the direct sum of the composition factors of the chosen Jordan-Hölder filtration; in particular, the limit is $\sigma$-polystable.

Setting $\lambda(t)=h^{-1} \lambda^{\prime}(t) h, \forall t \in \mathbb{R}$, we get that $\lambda \in X_{*}\left(G L(\mathbf{d})_{\sigma}\right)$ and $\widetilde{V}:=\lim _{t \rightarrow 0} \lambda(t) \cdot V$ exists and is $\sigma$-polystable. It is clear that $\widetilde{V}$ belongs to the closure of $\mathrm{GL}(\mathbf{d})_{\sigma} V$.

Finally, we know that the capacity $\mathbf{D}_{Q}(-, \sigma)$ is continuous (see [19, Section 7]) and $\mathrm{GL}(\mathbf{d})_{\sigma}$-invariant by Corollary 9. Consequently, for any $\sigma$-polystable representation $\widetilde{V} \in \overline{\mathrm{GL}(\mathbf{d})_{\sigma} V}$, we get that

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(\widetilde{V}, \sigma)=\chi_{\sigma}(A)^{2} \cdot \mathbf{D}_{Q}(A \cdot \widetilde{V}, \sigma)=\chi_{\sigma}(A)^{2},
$$

for any $A \in \mathcal{G}_{\sigma}(\widetilde{V})$.

We use Theorem 13 in an essential way to prove the following factorization of the capacity of quiver representations.

Theorem 16. Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a representation such that

$$
V(a)=\left(\begin{array}{cc}
V_{1}(a) & X(a) \\
0 & V_{2}(a)
\end{array}\right), \forall a \in Q_{1}
$$

where $V_{i} \in \operatorname{rep}\left(Q, \mathbf{d}_{i}\right), i \in\{1,2\}$, are representations of $Q$, and $X(a) \in \mathbb{R}^{\mathbf{d}_{1}(h a) \times \mathbf{d}_{2}(t a)}, \forall a \in$ $Q_{1}$. If $\sigma \cdot \operatorname{dim} V_{1}=0$ then

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}\left(V_{1}, \sigma\right) \cdot \mathbf{D}_{Q}\left(V_{2}, \sigma\right)
$$

Proof. Let us consider the representation $\widetilde{V} \in \operatorname{rep}(Q, \mathbf{d})$ given by

$$
\widetilde{V}(a)=\left(\begin{array}{cc}
V_{1}(a) & 0 \\
0 & V_{2}(a)
\end{array}\right), \forall a \in Q_{1} .
$$

We claim that $\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(\widetilde{V}, \sigma)$. Indeed, for each $t \in \mathbb{R}^{*}$, define

$$
\lambda(t)(x)=\left(\begin{array}{cc}
t \mathbf{I}_{\mathbf{d}_{1}(x)} & 0 \\
0 & \mathbf{I}_{\mathbf{d}_{2}(x)}
\end{array}\right), \forall x \in Q_{0} .
$$

Then, $(\lambda(t) \cdot V)(a)=\left(\begin{array}{cc}V_{1}(a) & t X(a) \\ 0 & V_{2}(a)\end{array}\right), \forall a \in O_{1}$, and so $\lim _{t \rightarrow 0} \lambda(t) V=\widetilde{V}$. We also have that $\chi_{\sigma}(\lambda(t))=t^{\sigma \cdot \mathbf{d}_{1}}=1, \forall t \in \mathbb{R}^{*}$, that is, $\lambda \in X_{*}\left(\mathrm{GL}(\mathbf{d})_{\sigma}\right)$. Using the fact that $\mathbf{D}_{Q}(-, \sigma)$ is continuous and GL(d) ${ }_{\sigma}$-invariant (see [19, Section 7] and Corollary 9), we get that

$$
\mathbf{D}_{Q}(\widetilde{V}, \sigma)=\lim _{t \rightarrow 0} \mathbf{D}_{Q}(\lambda(t) V, \sigma)=\mathbf{D}_{Q}(V, \sigma)
$$

In what follows, we show that

$$
\begin{equation*}
\mathbf{D}_{Q}(\widetilde{V}, \sigma)=\mathbf{D}_{Q}\left(V_{1}, \sigma\right) \cdot \mathbf{D}_{Q}\left(V_{2}, \sigma\right), \tag{15}
\end{equation*}
$$

which will prove the desired factorization formula.
If $\mathbf{D}_{Q}(V, \sigma)=0$ then $V$ is not $\sigma$-semi-stable by Theorem 1 . In this case, we get that either $V_{1}$ or $V_{2}$ is not $\sigma$-semi-stable. This follows from the short exact sequence $0 \rightarrow V_{1} \rightarrow V \rightarrow V_{2} \rightarrow 0$ of representations, and the fact that the category of $\sigma$-semistable representations of $Q$ is closed under extensions. Using Theorem 1 again, this is equivalent to $\mathbf{D}_{Q}\left(V_{1}, \sigma\right) \cdot \mathbf{D}_{Q}\left(V_{2}, \sigma\right)=0$, proving (15) when $\mathbf{D}_{Q}(V, \sigma)=0$.

Now, let us assume that $\mathbf{D}_{Q}(V, \sigma)>0$. In this case, we know from Theorem 13 that there exists a $\sigma$-polystable representation $V_{i}^{\prime} \in \overline{\mathrm{GL}\left(\mathbf{d}_{i}\right)_{\sigma} V_{i}}$ and a group element $A_{i} \in \mathrm{GL}\left(\mathbf{d}_{i}\right)$ such that $\left(A_{i} \cdot V_{i}^{\prime}, \sigma\right)$ is a geometric quiver datum and

$$
\mathbf{D}_{Q}\left(V_{i}, \sigma\right)=\chi_{\sigma}\left(A_{i}\right)^{2}, \forall i \in\{1,2\} .
$$

In fact, we can choose each $V_{i}^{\prime}$ to be a degeneration of $V_{i}$ along a 1-psg of GL( $\left.\mathbf{d}_{i}\right)_{\sigma}$. For $\widetilde{V}^{\prime}:=V_{1}^{\prime} \oplus V_{2}^{\prime} \in \operatorname{rep}(Q, \mathbf{d})$ and $A:=A_{1} \oplus A_{2} \in \mathrm{GL}(\mathbf{d})$, it is clear that $\widetilde{V}^{\prime} \in \overline{\mathrm{GL}(\mathbf{d})_{\sigma} \widetilde{V}}$ and $\left(A \cdot \widetilde{V}^{\prime}, \sigma\right)$ is a geometric quiver datum. Consequently, we obtain from Theorem 13(2) that

$$
\mathbf{D}_{Q}(\tilde{V}, \sigma)=\chi_{\sigma}(A)^{2}=\chi_{\sigma}\left(A_{1}\right)^{2} \cdot \chi_{\sigma}\left(A_{2}\right)^{2}=\mathbf{D}_{Q}\left(V_{1}, \sigma\right) \cdot \mathbf{D}_{Q}\left(V_{2}, \sigma\right)
$$

Remark 17. Let $V \in \operatorname{rep}(Q, \mathrm{~d})$ be a representation such that along every arrow, $V$ is an upper triangular block matrix whose block entries are given by representations $V_{1}, \ldots, V_{n}$. Then Theorem 16 implies that

$$
\mathbf{D}_{Q}(V, \sigma)=\prod_{i=1}^{n} \mathbf{D}_{Q}\left(V_{i}, \sigma\right)
$$

### 4.2 Extremisable quiver data

For a representation $V \in \operatorname{rep}(Q, \mathbf{d})$ and an $m$-tuple $Y=\left(Y_{1}, \ldots, Y_{m}\right)$ with $Y_{j} \in \mathcal{S}_{\mathbf{d}\left(w_{j}\right)}^{+}$, $j \in[m]$, we set

$$
\mathbf{D}_{Q}(V, \sigma ; Y):=\frac{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)^{\sigma_{+}\left(V_{i}\right)}}{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{\sigma_{-}\left(w_{j}\right)}}
$$

Definition 18. Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be such that $\mathrm{D}_{Q}(V, \sigma)>0$. We say that $(V, \sigma)$ is gaussian-extremisable if there exists an $m$-tuple $Y=\left(Y_{j}\right)_{j=1}^{m}$ with $Y_{j} \in \mathcal{S}_{\mathbf{d}\left(w_{j}\right)}^{+}, j \in[m]$, such that

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(V, \sigma ; Y)
$$

We call any such tuple $Y$ a gaussian extremiser for $(V, \sigma)$.

Remark 19. Let $(V, \sigma)$ be a gaussian-extremisable quiver datum with gaussian extremiser $Y=\left(Y_{j}\right)_{j=1}^{m}$. We claim that for any $A=(A(x))_{x \in Q_{0}} \in \operatorname{GL}(\mathbf{d}),(A \cdot V, \sigma)$ is
gaussian-extremisable with gaussian extremiser

$$
\begin{equation*}
\tilde{Y}:=\left(\left(A\left(w_{j}\right)^{T}\right)^{-1} \cdot Y_{j} \cdot A\left(w_{j}\right)^{-1}\right)_{j \in[m]} \tag{16}
\end{equation*}
$$

Indeed, it is straightforward to see that

$$
\mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(V, \sigma ; Y)=\left(\chi_{\sigma}(A)\right)^{2} \cdot \mathbf{D}_{Q}(A \cdot V, \sigma ; \widetilde{Y})
$$

Using Corollary 9, we then get that

$$
\mathbf{D}_{Q}(A \cdot V, \sigma)=\left(\chi_{\sigma}(A)\right)^{-2} \cdot \mathbf{D}_{Q}(V, \sigma)=\mathbf{D}_{Q}(A \cdot V, \sigma ; \widetilde{Y}),
$$

and this proves our claim.

Our next result gives necessary and sufficient conditions for ( $V, \sigma$ ) to be gaussian-extremisable and explains how to construct all the gaussian extremisers from $\mathcal{G}_{\sigma}(V)$.

Theorem 20. Let $(V, \sigma)$ be a quiver datum with $V \in \operatorname{rep}(Q, \mathbf{d})$ and $\mathbf{D}_{Q}(V, \sigma)>0$. Then $V$ is $\sigma$-polystable if and only if ( $V, \sigma$ ) is gaussian-extremisable. If this is the case, the gaussian extremisers of $(V, \sigma)$ are the $m$-tuples

$$
\left(A\left(w_{j}\right)^{T} \cdot A\left(w_{j}\right)\right)_{j \in[m]} \text { with } A \in \mathcal{G}_{\sigma}(V)
$$

Proof. $(\Longrightarrow)$ Let $(V, \sigma)$ be a quiver datum such that $V$ is $\sigma$-polystable, and pick an arbitrary $A \in \mathcal{G}_{\sigma}(V)$. Then $(A \cdot V, \sigma)$ is geometric, and hence it is gaussian extremisable with gaussian extremiser $\left(\mathbf{I}_{\mathbf{d}\left(w_{j}\right)}\right)_{j=1}^{m}$. This observation combined with (16) shows that $(V, \sigma)$ is gaussian extremisable with gaussian extremiser $\left(A\left(w_{j}\right)^{T} \cdot A\left(w_{j}\right)\right)_{j \in[m]}$. $(\Longleftarrow)$ Let us assume now that $(V, \sigma)$ is gaussian extremisable and let $Y=\left(Y_{j}\right)_{j=1}^{m}$ be a gaussian extremiser for $(V, \sigma)$. For each $i \in[n]$, let

$$
M_{i}=\sum_{j \in[m]} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right) \in \mathbb{R}^{\mathbf{d}\left(v_{i}\right) \times \mathbf{d}\left(v_{i}\right)} .
$$

Since $\mathbf{D}_{Q}(V, \sigma)$ is assumed to be non-zero and

$$
\mathbf{D}_{Q}(V, \sigma)=\frac{\prod_{i \in[n]} \operatorname{det}\left(M_{i}\right)^{\sigma_{+}\left(V_{i}\right)}}{\prod_{j \in[m]} \operatorname{det}\left(Y_{j}\right)^{\sigma_{-}\left(w_{j}\right)}},
$$

we conclude that each $M_{i}$ is a positive definite matrix. Define

$$
A\left(v_{i}\right)=M_{i}^{\frac{1}{2}}, \forall i \in[n], \text { and } A\left(w_{j}\right)=Y_{j}^{\frac{1}{2}}, \forall j \in[m]
$$

Claim: If $A:=\left(A\left(V_{i}\right), A\left(w_{j}\right)\right)_{i \in[n], j \in[m]}$ then $A \in \mathcal{G}_{\sigma}(V)$.

Proof of Claim. We begin by checking that $A \cdot V$ satisfies equation (10). We have that

$$
\begin{aligned}
& \sum_{j \in[m]} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}}(A \cdot V)^{T}(a) \cdot(A \cdot V)(a)\right)= \\
= & \sum_{j \in[m]} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} A(t a)^{-T} \cdot V(a)^{T} \cdot A(h a)^{T} \cdot A(h a) \cdot V(a) \cdot A(t a)^{-1}\right) \\
= & \sum_{j \in[m]} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} M_{i}^{-\frac{1}{2}} \cdot V(a)^{T} \cdot Y_{j}^{\frac{1}{2}} \cdot Y_{j}^{\frac{1}{2}} \cdot V(a) \cdot M_{i}^{-\frac{1}{2}}\right) \\
= & M_{i}^{-\frac{1}{2}} \cdot\left(\sum_{j \in[m]} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right) \cdot M_{i}^{-\frac{1}{2}} \\
= & M_{i}^{-\frac{1}{2}} \cdot M_{i} \cdot M_{i}^{-\frac{1}{2}}=\mathrm{I}_{\mathrm{d}\left(V_{i}\right)}, \forall i \in[n],
\end{aligned}
$$

To prove (17), we adapt the proof strategy for the implication $(b) \Longrightarrow(c)$ in [4, Proposition 3.6] to our more general quiver set-up. After taking logarithms in the
formula for the capacity in Lemma 8, we get that $Y$ is a minimiser for the quantity

$$
\begin{equation*}
\sum_{i \in[n]} \sigma_{+}\left(v_{i}\right) \log \left(\operatorname{det}\left(\sum_{j \in[m]} \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)\right)-\sum_{j \in[m]} \sigma_{-}\left(w_{j}\right) \log \left(\operatorname{det}\left(Y_{j}\right)\right) . \tag{18}
\end{equation*}
$$

Now, let us fix $j \in[m]$ and let $Q_{j} \in \mathbb{R}^{\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(w_{j}\right)}$ be an arbitrary symmetric matrix. Replacing $Y_{j}$ by $Y_{j}+\epsilon Q_{j}$ in (18), we can see that $\epsilon=0$ is a minimiser for

$$
A(\epsilon)-B(\epsilon)
$$

where

$$
\begin{aligned}
& A(\epsilon)=\sum_{i \in[n]} \sigma_{+}\left(V_{i}\right) \log \left(\operatorname{det}\left(M_{i}+\epsilon \sigma_{-}\left(w_{j}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Q_{j} \cdot V(a)\right)\right)\right) \\
= & \sum_{i \in[n]} \sigma_{+}\left(V_{i}\right) \log \left(\operatorname{det} M_{i}\right)+\sum_{i \in[n]} \sigma_{+}\left(V_{i}\right) \log \left(\operatorname{det}\left(\mathrm{I}_{\mathrm{d}\left(V_{i}\right)}+\epsilon \sigma_{-}\left(w_{j}\right) M_{i}^{-1}\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Q_{j} \cdot V(a)\right)\right)\right)
\end{aligned}
$$

and

$$
\begin{aligned}
& B(\epsilon)=\sum_{j^{\prime} \in[m] j^{\prime} \neq j} \sigma_{-}\left(w_{j^{\prime}}\right) \log \left(\operatorname{det}\left(Y_{j^{\prime}}\right)\right)+\sigma_{-}\left(w_{j}\right) \log \left(\operatorname{det}\left(Y_{j}+\epsilon Q_{j}\right)\right) \\
= & \sum_{j^{\prime} \in[m]} \sigma_{-}\left(w_{j^{\prime}}\right) \log \left(\operatorname{det}\left(Y_{j^{\prime}}\right)\right)+\sigma_{-}\left(w_{j}\right) \log \left(\operatorname{det}\left(\mathbf{I}_{\mathbf{d}\left(w_{j}\right)}+\epsilon Y_{j}^{-1} \cdot O_{j}\right)\right) .
\end{aligned}
$$

Since $\left.\frac{d}{d \epsilon} \log (\operatorname{det}(\mathbf{I}+\epsilon Q))\right|_{\epsilon=0}=\operatorname{Tr}(Q)$ for any symmetric matrix $Q$, we get that

$$
\begin{aligned}
0 & =\left.\frac{d}{d \epsilon}(A(\epsilon)-B(\epsilon))\right|_{\epsilon=0} \\
& =\sum_{i \in[n]} \sigma_{+}\left(v_{i}\right) \operatorname{Tr}\left(\sigma_{-}\left(w_{j}\right) M_{i}^{-1}\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Q_{j} \cdot V(a)\right)\right)-\sigma_{-}\left(w_{j}\right) \operatorname{Tr}\left(Y_{j}^{-1} \cdot Q_{j}\right) \\
& =\sigma_{-}\left(w_{j}\right)\left(\sum_{i \in[n]} \operatorname{Tr}\left(\sigma_{+}\left(V_{i}\right) M_{i}^{-1}\left(\sum_{a \in \mathcal{A}_{i, j}} V(a)^{T} \cdot Q_{j} \cdot V(a)\right)\right)-\operatorname{Tr}\left(Y_{j}^{-1} \cdot Q_{j}\right)\right) .
\end{aligned}
$$

Rearranging the factors inside the trace, we obtain that

$$
\begin{equation*}
\operatorname{Tr}\left(Q_{j} \cdot\left(\sum_{i \in[n]} \sigma_{+}\left(V_{i}\right)\left(\sum_{a \in \mathcal{A}_{i j}} V(a) \cdot M_{i}^{-1} \cdot V(a)^{T}\right)-Y_{j}^{-1}\right)\right)=0 \tag{19}
\end{equation*}
$$

holds for all symmetric matrices $Q_{j}$. Since $\sum_{i \in[n]} \sigma_{+}\left(V_{i}\right)\left(\sum_{a \in \mathcal{A}_{i j}} V(a) \cdot M_{i}^{-1} \cdot V(a)^{T}\right)-Y_{j}^{-1}$ is a symmetric matrix, we can see that (19) yields the desired formula (17).

Finally, for each $j \in[m]$, we get via (17) that

$$
\begin{aligned}
& \sum_{i \in[n]} \sigma_{+}\left(V_{i}\right)\left(\sum_{a \in \mathcal{A}_{i, j}}(A \cdot V)(a) \cdot(A \cdot V)^{T}(a)\right)= \\
= & A\left(w_{j}\right) \cdot\left(\sum_{i \in[n]} \sigma_{+}\left(V_{i}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a) \cdot A\left(v_{i}\right)^{-1} \cdot A\left(V_{i}\right)^{-T} \cdot V^{T}(a)\right)\right) \cdot A\left(w_{j}\right)^{T} \\
= & A\left(w_{j}\right) \cdot\left(\sum_{i \in[n]} \sigma_{+}\left(V_{i}\right)\left(\sum_{a \in \mathcal{A}_{i, j}} V(a) \cdot M_{i}^{-1} \cdot V^{T}(a)\right)\right) \cdot A\left(w_{j}\right)^{T} \\
= & A\left(w_{j}\right) \cdot Y_{j}^{-1} \cdot A\left(w_{j}\right)^{T}=\mathbf{I}_{\mathbf{d}\left(w_{j}\right)},
\end{aligned}
$$

$$
A_{2} \cdot V \in \mathbf{O}(\mathbf{d}) \cdot\left(A_{1} \cdot V\right)
$$

where $\mathbf{O}(\mathbf{d})$ denotes the subgroup of $G L(\mathbf{d})$ consisting of all tuples of orthogonal matrices. In other words,

$$
\begin{equation*}
A_{2}^{-1} \cdot h \cdot A_{1} \in \operatorname{Stab}_{\mathrm{GL}(\mathbf{d})}(V)=\operatorname{End}_{Q}(V)^{\times} \text {for some } h \in \mathbf{O}(\mathbf{d}) . \tag{20}
\end{equation*}
$$

To prove the first claim, let us assume that $V$ is $\sigma$-stable and $\operatorname{End}_{Q}(V)=\left\{\left(\lambda \mathbf{I}_{\mathbf{d}(X)}\right)_{X \in Q_{0}}\right\}$ $\lambda \in \mathbb{R}\}$. We know from Theorem 20 that $(V, \sigma)$ is gaussian-extremisable, and let $A_{1}, A_{2} \in$ $\mathcal{G}_{\sigma}(V)$. Then, by (20), we can write

$$
A_{2}=\lambda\left(h \cdot A_{1}\right)
$$

for some $h \in \mathbf{O}(\mathbf{d})$ and $\lambda \in \mathbb{R}^{\times}$. Consequently, we get that

$$
A_{2}\left(w_{j}\right)^{T} \cdot A_{2}\left(w_{j}\right)=\lambda^{2}\left(A_{1}\left(w_{j}\right)^{T} \cdot A_{1}\left(w_{j}\right)\right), \forall j \in[m] .
$$

It now follows from Theorem 20 that $(V, \sigma)$ has unique gaussian extremisers, up to scaling.

For the second claim, let us assume ( $V, \sigma$ ) has unique gaussian extremisers. By Theorem 20, we know that $V$ is $\sigma$-polystable. Let us assume for a contradiction that $V=V_{1} \oplus V_{2}$ with $V_{1} \in \operatorname{rep}\left(Q, \mathbf{d}_{1}\right), V_{1} \in \operatorname{rep}\left(Q, \mathbf{d}_{2}\right)$, two proper $\sigma$-polystable subrepresentations of $V$. So we can choose $A_{1} \in \mathcal{G}_{\sigma}\left(V_{1}\right)$ and $A_{2} \in \mathcal{G}_{\sigma}\left(V_{2}\right)$ by Theorem 20. Then, for any two scalars $\lambda_{1}, \lambda_{2} \in \mathbb{R}^{\times}$with $\left|\lambda_{1}\right| \neq\left|\lambda_{2}\right|$, the gaussian extermisers for $(V, \sigma)$ corresponding to

$$
\left(\begin{array}{cc}
A_{1} & 0 \\
0 & A_{2}
\end{array}\right) \text { and }\left(\begin{array}{cc}
\lambda_{1} A_{1} & 0 \\
0 & \lambda_{2} A_{2}
\end{array}\right)
$$

are not a scalar multiple of each other (contradiction). This finishes the proof.

### 4.3 Proof of Theorem 2

Parts (1) and (2) of Theorem 2 are proved in Theorem 13. Part (3) is proved in Theorem 16. Finally parts (4) and (5) are proved in Theorems 20 and 21.

## 5 Structural Results for Brascamp-Lieb Constants for Ouiver Data

In this section we explain how to rephrase our main results, Theorems 1 and 2, in terms of BL constants. Let $Q=\left(Q_{0}, Q_{1}, t, h\right)$ be a bipartite quiver with set of source vertices
$Q_{0}^{+}=\left\{v_{1}, \ldots, v_{n}\right\}$, and set of sink vertices $Q_{0}^{-}=\left\{w_{1}, \ldots, w_{m}\right\}$. Denote by $\mathcal{A}_{i, j}$ the set of all arrows from $v_{i}$ to $w_{j}$ for all $i \in[n]$ and $j \in[m]$.

Let $\mathbf{d}$ be a dimension vector of $Q$ and $\mathbf{p}=\left(p_{1}, \ldots, p_{m}\right)$ an $m$-tuple of positive rational numbers such that

$$
\begin{equation*}
\sum_{i=1}^{n} \mathbf{d}\left(v_{i}\right)=\sum_{j=1}^{m} p_{j} \cdot \mathbf{d}\left(w_{j}\right) \tag{21}
\end{equation*}
$$

A d-dimensional representation $V$ of $Q$ is said to be $\mathbf{p}$-semi-stable if

$$
\sum_{i=1}^{n} \operatorname{dim}_{\mathbb{R}} V^{\prime}\left(v_{i}\right) \leq \sum_{j=1}^{m} p_{j} \operatorname{dim}_{\mathbb{R}} V^{\prime}\left(w_{j}\right)
$$

for all subrepresentations $V^{\prime} \leq V$. We say that $V$ is $p$-stable if the inequality above is strict for all proper subrepresentations $V^{\prime}$ of $V$. A representation is said to be ppolystable if it is a finite direct sum of $\mathbf{p}$-stable representations.

Let $\omega$ be the least common denominator of $p_{1}, \ldots, p_{m}$. Then the weight $\sigma_{\mathbf{p}}$ of $Q$ induced by $\mathbf{p}$ is defined by

$$
\sigma_{\mathbf{p}}\left(v_{i}\right)=\omega, \forall i \in[n], \text { and } \sigma_{\mathbf{p}}\left(w_{j}\right)=-\omega \cdot p_{j}, \forall j \in[m]
$$

We also denote by $\chi_{\mathbf{p}}$ the character of GL(d) induced by $\sigma_{\mathbf{p}}$, that is,

$$
\chi_{\mathbf{p}}(A)=\prod_{i=1}^{n} \operatorname{det}\left(A\left(v_{i}\right)\right)^{\omega} \cdot \prod_{j=1}^{m} \operatorname{det}\left(A\left(w_{j}\right)\right)^{-w p_{j}}, \forall A \in \mathrm{GL}(\mathbf{d}) .
$$

Now, let $(V, \mathbf{p})$ be a quiver datum with $V \in \operatorname{rep}(Q, \mathbf{d})$. Then it is clear that

- (21) is equivalent to $\sigma_{\mathbf{p}} \cdot \mathbf{d}=0$; and
- $V$ being p-semi-stable/stable/polystable is equivalent to $V$ being $\sigma_{\mathbf{p}}$-semistable/stable/polystable.

Recall that the BL constant associated to the quiver datum ( $V, \mathbf{p}$ ) is

$$
\begin{equation*}
\mathrm{BL}_{Q}(V, \mathbf{p})=\sup \left\{\left(\frac{\prod_{j=1}^{m} \operatorname{det}\left(Y_{j}\right)^{p_{j}}}{\prod_{i=1}^{n} \operatorname{det}\left(\sum_{j=1}^{m} p_{j}\left(\sum_{a \in \mathcal{A}_{i j}} V(a)^{T} \cdot Y_{j} \cdot V(a)\right)\right)}\right)^{\frac{1}{2}}\right\} \tag{22}
\end{equation*}
$$

 We say that $(V, \mathbf{p})$ is feasible if $\mathrm{BL}_{Q}(V, \mathbf{p})<\infty$. A feasible quiver datum $(V, \mathbf{p})$ is said to be gaussian-extremisable if there exist positive definite matrices $Y_{j} \in \mathbb{R}^{\mathbf{d}\left(w_{j}\right) \times \mathbf{d}\left(w_{j}\right)}, j \in[m]$, for which the supremum is attained in (22). If this is the case, we call such an $m$-tuple $\left(Y_{1}, \ldots, Y_{m}\right)$ a gaussian extremiser for ( $V, \mathbf{p}$ ).

When working with BL constants, we "scale" the definition of a geometric quiver datum as follows: We say that $(V, \mathbf{p})$ is a geometric $B L$ quiver datum if

$$
\begin{equation*}
\sum_{j=1}^{m} p_{j} \sum_{a \in \mathcal{A}_{i, j}}(V(a))^{T} \cdot V(a)=\mathbf{I}_{\mathrm{d}\left(v_{i}\right)}, \forall i \in[n] \tag{23}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{i=1}^{n} \sum_{a \in \mathcal{A}_{i, j}} V(a) \cdot(V(a))^{T}=\mathrm{I}_{\mathrm{d}\left(w_{j}\right)}, \forall j \in[m] \tag{24}
\end{equation*}
$$

(When $Q$ is the $m$-subspace quiver $\mathcal{Q}_{m}$, this is the definition of a geometric datum introduced in [4, Section 2].)

Let us now explain the relationship between the algebraic varieties $\mathcal{B L}_{\mathbf{p}}(V)$ and $\mathcal{G}_{\sigma_{\mathbf{p}}}(V)$. For a representation $V \in \operatorname{rep}(Q, \mathbf{d})$, consider the real algebraic variety

$$
\mathcal{B} \mathcal{L}_{\mathbf{p}}(V)=\{A \in \mathrm{GL}(\mathbf{d}) \mid(A \cdot V, \mathbf{p}) \text { is a geometric BL quiver datum }\}
$$

For $A \in \mathrm{GL}(\mathbf{d})$, define $\widetilde{A} \in \mathrm{GL}(\mathbf{d})$ by $\widetilde{A}\left(v_{i}\right)=A\left(v_{i}\right), \forall i \in[n]$, and $\widetilde{A}\left(w_{j}\right)=\omega^{-\frac{1}{2}} \cdot A\left(w_{j}\right)$, $\forall j \in[m]$. Then it is straightforward to check that
(i) $A \in \mathcal{B} \mathcal{L}_{\mathbf{p}}(V) \Longleftrightarrow \widetilde{A} \in \mathcal{G}_{\sigma_{\mathbf{p}}}(V)$;
(ii) $\omega^{N} \cdot \chi_{\mathbf{p}}(A)^{2}=\chi_{\sigma_{\mathrm{p}}}(\widetilde{A})^{2}$;
(iii) for any p-polystable representation $V \in \operatorname{rep}(Q, \mathbf{d})$, Theorem 13(2) and Remark 11(2) yield

$$
\mathrm{BL}_{Q}(V, \mathbf{p})=\frac{1}{\sqrt[2 \omega]{\omega^{-N} \cdot \mathbf{D}_{Q}\left(V, \sigma_{\mathbf{p}}\right)}}=\frac{1}{\sqrt[2 \omega]{\omega^{-N} \cdot \chi_{\sigma_{\mathbf{p}}}(\tilde{A})^{2}}}=\frac{1}{\sqrt[2 \omega]{\chi_{\mathbf{p}}(A)^{2}}}
$$

for any $A \in \mathcal{B} \mathcal{L}_{\mathbf{p}}(V)$; and
(iv) an $m$-tuple $\left(Y_{1}, \ldots, Y_{m}\right)$ of positive definite matrices is a gaussian extremiser for $(V, \mathbf{p})$ if and only if $\left(\omega^{-1} \cdot Y_{1}, \ldots, \omega^{-1} \cdot Y_{m}\right)$ is a gaussian extremiser for $\left(V, \sigma_{\mathbf{p}}\right)$.

Consequently, applying Theorems 1 and 2 to this set-up yields the following structural result on BL constants for arbitrary bipartite quivers.

Theorem 22. Keep the same notation as above.

1. (Finitness of BL constants) Let $(V, \mathbf{p})$ be a quiver datum with $V \in \operatorname{rep}(Q, \mathbf{d})$. Then $\mathrm{BL}_{Q}(V, \mathbf{p})<\infty$ if and only if $V$ is $\mathbf{p}$-semi-stable.
2. (Kempf-Ness theorem for real quiver representations) Let ( $V, \mathbf{p}$ ) be a feasible quiver datum with $V \in \operatorname{rep}(Q, \mathbf{d})$ and consider the real algebraic variety

$$
\mathcal{B} \mathcal{L}_{\mathbf{p}}(V):=\{A \in \mathrm{GL}(\mathbf{d}) \mid(A \cdot V, \mathbf{p}) \text { is a geometric BL quiver datum }\}
$$

Then

$$
\mathcal{B} \mathcal{L}_{\mathbf{p}}(V) \neq \emptyset \Longleftrightarrow V \text { is } \mathbf{p}-\text { polystable }
$$

3. (Character formula for BL constants) Let ( $V, \mathbf{p}$ ) be a feasible quiver datum with $V \in \operatorname{rep}(Q, \mathbf{d})$. Then there exists a p-polystable representation $\widetilde{V}$ such that $\widetilde{V} \in \overline{\mathrm{GL}(\mathbf{d})_{\mathbf{p}} V}$. Furthermore, for any such $\widetilde{V}$, the following formula holds:

$$
\mathrm{BL}_{Q}(V, \mathbf{p})=\mathrm{BL}_{Q}(\widetilde{V}, \mathbf{p})=\left|\chi_{\mathbf{p}}(A)\right|^{-\frac{1}{\omega}}, \forall A \in \mathcal{B} \mathcal{L}_{\mathbf{p}}(\widetilde{V})
$$

4. (Factorization of BL constants) Let $V \in \operatorname{rep}(Q, \mathbf{d})$ be a d-dimensional representation. Assume that

$$
V(a)=\left(\begin{array}{cc}
V_{1}(a) & X(a) \\
0 & V_{2}(a)
\end{array}\right), \forall a \in Q_{1},
$$

where $V_{i} \in \operatorname{rep}\left(Q, \mathbf{d}_{i}\right), i \in\{1,2\}$, are representations of $Q$, and $X(a) \in$ $\mathbb{R}^{\mathbf{d}_{1}(h a) \times \mathbf{d}_{2}(t a)}$ for every $a \in Q_{1}$. If $\mathbf{p}$ and $\operatorname{dim}_{V_{1}}$ are orthogonal then

$$
\mathrm{BL}_{Q}(V, \mathbf{p})=\mathrm{BL}_{Q}\left(V_{1}, \mathbf{p}\right) \cdot \mathrm{BL}_{Q}\left(V_{2}, \mathbf{p}\right)
$$

5. (Gaussian extremisers: existence) A feasible quiver datum ( $V, \mathbf{p}$ ) with $V \in$ $\operatorname{rep}(Q, \mathbf{d})$ is gaussian-extremisable if and only if $V$ is $\mathbf{p}$-polystable. If this is the case, the gaussian extremisers of $(V, \mathbf{p})$ are the $m$-tuples of matrices

$$
\left(A\left(w_{j}\right)^{T} \cdot A\left(w_{j}\right)\right)_{j \in[m]} \text { with } A \in \mathcal{B} \mathcal{L}_{\mathbf{p}}(V)
$$

6. (Gaussian extremisers: uniqueness) If a feasible quiver datum ( $V, \mathbf{p}$ ) with $V \in \operatorname{rep}(Q, \mathbf{d})$ has unique gaussian extremisers (up to scaling) then $V$ is $\mathbf{p}$ stable. Conversely, if $V$ is p-stable and $\operatorname{End}_{Q}(V)=\mathbb{R}$ then $(V, \mathbf{p})$ has unique gaussian extremisers (up to scaling).

## Remark 23.

1. In a sequel to the current work, we plan to further study the capacity and BL-constants associated to quiver data by focusing on the constructive, algorithmic aspects of the real algebraic varieties $\mathcal{G}_{\sigma}(V)$ and $\mathcal{B} \mathcal{L}_{\mathbf{p}}(V)$ introduced in this paper.
2. The main results of this paper have already found applications to Edmonds' Problem in algebraic complexity (see [12]) and simultaneous robust subspace recovery in machine learning (see [13]). Further applications of Theorem 13 and Proposition 14 to Radial Isotropy and Paulsen's Problem for matrix frames will appear in a future paper on the subject.

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